

# Chapter 5 – Implementation Model for Imperative Languages

## Introduction to Programming Languages

### First Edition, 2013

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## Topics Covered

- Introduction
- Abstract Computing Machine
- Translating Control Abstractions
- Static Allocation
- Hybrid Allocation
- Implementing Parameter Passing
- Low Level Behavior of Recursive Procedures
- Implementing Exception Handlers
- Summary

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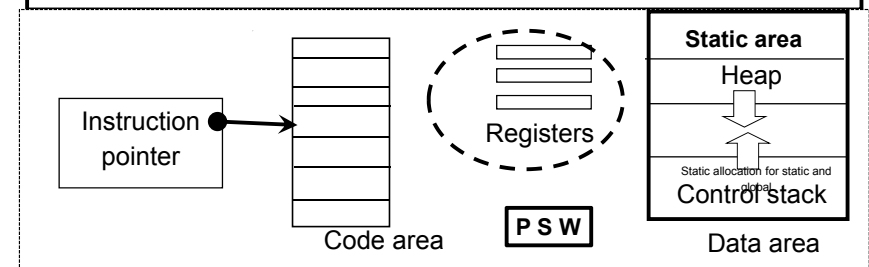
## Memory Allocation Schemes

- **Static allocation**
  - Fixed memory allocation at compile time; no runtime growth
  - Wastage of memory if not used; efficient due to direct memory access
  - Does not support recursive procedures, recursive, and dynamic data structures.
- **Stack based allocation**
  - Memory is allocated on control stack frame by frame at runtime
  - Supports recursive procedures, but not recursive data structures.
  - Uses pointer based access. Is slower than static allocation
- **Heap based allocation**
  - Memory allocation on demand in a common memory called heap.
  - Deallocated manually or automatically
  - Supports recursive procedures and recursive data structures
  - Memory recycling overhead up to 30%. Pointer access overhead
- **Hybrid allocation**
  - Combination of the above three schemes to exploit the advantages

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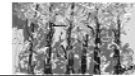
## Abstract Computing Machine

- Consists of data area, code area, instruction pointer, registers, and program status word – a set of flags
  - Code area is a sequence of low level instructions
  - Instruction pointer to step through the instructions in the code area
  - Data area is a pair of the linear structures (*heap*, *control stack*) growing in opposite direction
  - Control stack is a sequence of frames holding the store of procedures
  - Control changes either through IP or by jump statements



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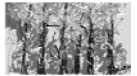
## Data Area



- Each frame is indexable and contains
  - Local dynamic variables
  - Image of the registers that would be updated in the called subprogram
  - Various pointers to access data-entities and frames
  - The frozen state of the calling subprogram
  - Simple dynamic objects that do not outlive the subprogram
  - Parameters passed to the called subprogram.
- Memory access: direct, indirect, offset based
  - Memory location in a frame are accessed using  $d[FP + \text{offset}]$ . Indirect memory access is  $d[d[FP + \text{Offset}]]$ .
- Control stack during program invocation
  - Calling programs frame is saved
  - Frame of the called program is placed on top of the stack
  - Various pointers are updated to link the code area and data area of the called subprogram and calling program
  - Code area jumps from the calling program to the called program

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## Code Area and Memory Access



- Code area is a sequence of low level instructions
- Instructions are accessed using  $c[\text{index}]$
- Instructions are of different types
  - Arithmetic operations; logical operations; conditional jumps; unconditional jumps; accessing data from memory; storing data into memory; moving data from one register to another register
- Types of memory access
  - Direct access :- suitable for static variables
  - Indirect access :- uses a pointer, provides independence from fixed locations; overhead of an additional access
  - Offset based access :- used to access memory locations in frame
- Status flags
  - Negation bit, zero bit, overflow bit, Boolean flag are set by various arithmetic and logical instructions

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## Translating Control Abstractions



- Process
  - Make a control flow diagram of the high level control abstractions
  - Map control flow diagrams to low level instructions using a combination of conditional jumps and low level instructions
- Control flow diagram  $\rightarrow$  low level abstract instructions
  - Control flow diagrams are two dimensional while low level instructions are single dimensional
  - Sequence of contiguous single dimensional statements are connected using conditional branches if needed
  - Registers are used for temporary storage and scratchpad computations

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## Translating Expressions



- Process involves
  - Reading the variables from the memory locations
  - Evaluating the subexpressions
  - Storing the common subexpressions in a register to avoid reevaluation of the common subexpressions
  - Laws of computation such as associativity, commutativity, and distributivity are used for simplification
- Example:  $(X + Y + 5) + 2 * (X + Y)$ 
  - load X, R1
  - add Y, R1, R2
  - add #5, R2, R3
  - multiply #2, R2, R4 % looking up the common subexpression
  - add R3, R4, R3

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## Translating Assignment Statement

### ■ Assignment state includes

- Evaluation of the right hand side expression
- Writing into the memory-location of the variable on the left hand side

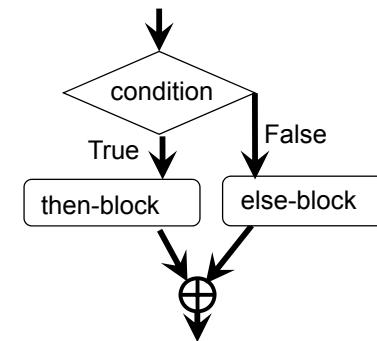
### ■ Example: $x = y + 5$

load y, R0 % load the value of y in register R0  
 add # 5, R0, R0 % add 5 to the value in the register R0  
 store R0, x % store the value of R0 in the variable X

## Translating if-then-else Statement

### ■ Process

- Evaluate the predicate
- Set the status flags based upon the predicate evaluation
- Based upon the status flags branch to execute either the block of statements in then-part or the block of statements in the else-part.

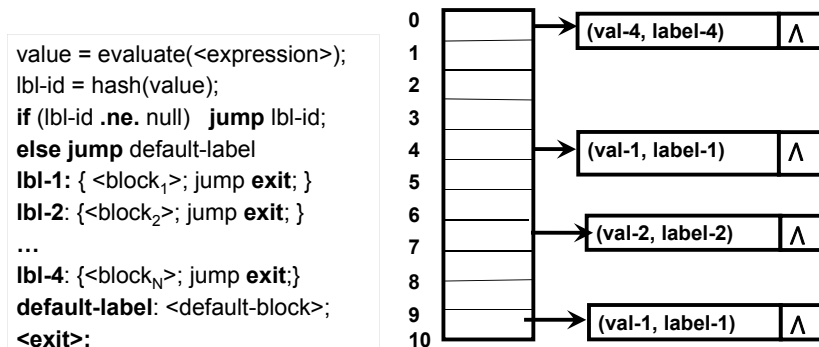


1. evaluate not (<condition>)
2. branch-on-true **else**
3. execute <then-block>
4. jump **exit**
5. **else:** execute <else-block>
6. **exit:**

## Translating Case Statement

### ■ Can be translated to low level instructions

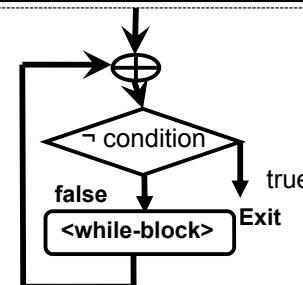
- Use a set of if-then-else statements, or
- Use hash table. Hash table contains a triple of the form (expected-value, label-number, pointer to next triple). After evaluating the expression, the control jumps to the index given by the hash-value of the evaluated expression.



## Translating While-loop

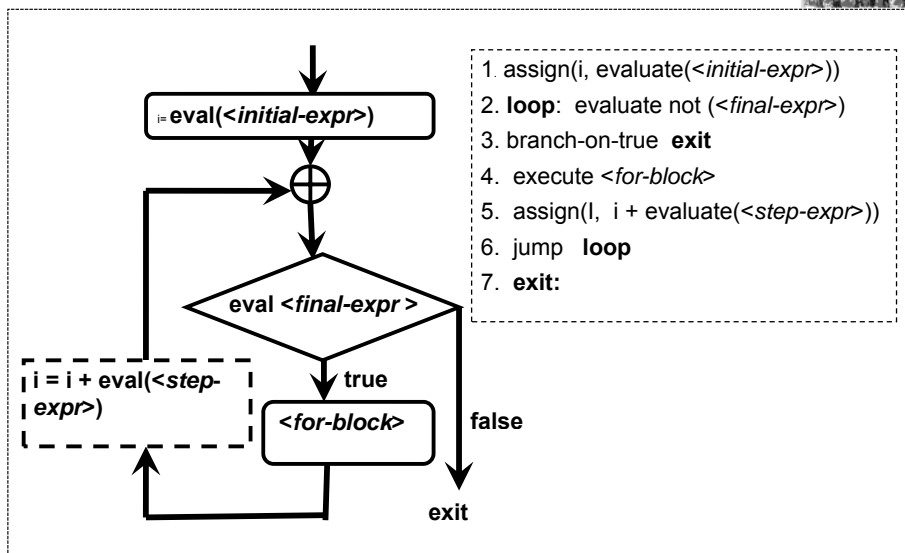
### ■ Process

- Make the control flow diagram using negation of the condition-test.
- Label the entry point of while-loop and the exit-point.
- Check for the negation of the condition and jump to the exit on success.
- Fall through the then part.
- Add an unconditional jump after then part to the exit-point.



1. **loop:** evaluate not (<condition>)
2. branch-on-true **exit**
3. execute <while-block>
4. jump-to **loop**
6. **exit:**

## For-loop Translation



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## Static Allocation

### ■ Allocation

- Memory is allocated at compile time, and can not grow
- Wastes memory space as all the allocated memory allocation may not be used in a single invocation
- Does not support recursive procedure and recursive data structures
- **Advantage:** direct memory allocation is efficient

### ■ Data area represented as fixed one dimensional array

- Data elements are accessed as d[index]
- Code area is accessed as c[index]

### ■ Program invocation

- A return pointer that stores the next instruction in the calling program to be executed is stored in the activation record of the called procedure.
- Unconditional jump to jump to first instruction of the called program
- Return from the subroutine takes the location from the return pointer, and makes unconditional jump.

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## Example – Static Allocation

```

PROGRAM MAIN
DIMENSION M[4]
INTEGER I, J, Max
COMMON /DATA/ M[4], MAX
DO 20 I = 1, 4, 1
20 READ(M[I])
CALL FIND_MAX
END
  
```

```

0. assign(d[5], 1)
1. cmp(d[5], 4)
2. brgt (ip + 4) % ip = 6
3. read(d[0 + d[5]])
4. assign(d[5], d[5] + 1)
5. jump(ip - 4)
6. assign(d[<R>], ip + 2)
7. jump(ip + <S>)
8. halt
  
```

0	M[1]
1	M[2]
2	M[3]
3	M[4]
4	MAX
5	I
6	J

```

SUBROUTINE FIND_MAX
DIMENSION M[4]
INTEGER MAX, I
COMMON /DATA/, M[4], MAX
MAX = M[1]
DO 10 I = 2, 4, 1
10 IF (M[I] > MAX) MAX = M[I]
RETURN
  
```

```

0. assign(d[4], d[0])
1. assign(d[6], 2)
2. cmp(d[6], 4)
3. brgt (ip + 6) % ip = 9
4. cmp(d[0 + d[6]], d[4])
5. brle (ip + 2) % ip = 7
6. assign(d[4], d[0 + d[6]])
7. assign(d[6], d[6] + 1)
8. jump(ip - 6)
9. jump(d[5])
  
```

0	M[1]
1	M[2]
2	M[3]
3	M[4]
4	MAX
5	return
6	I

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## Linking Compiled Code

### ■ Multiple program units are compiled separately

### ■ Separately compiled units lack

- Information about where to jump when a subprogram is called
- How much to jump when a subprogram is called

### ■ Program linking joins the

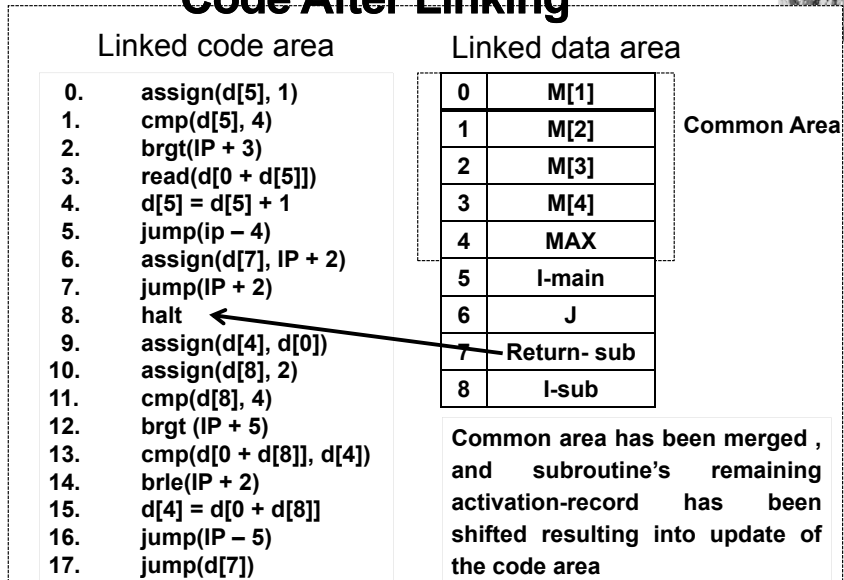
- Code areas of the compiled programs into one single large code area
- Data areas of the compiled programs into one single large data area
- The order of compiled code is independent of the calling order of the programs. Rather it depends on the order in the linking commands

### ■ Effect of linking

- The return location and the location of the first instruction is the called routine is known, and filled in
- The memory location of variables of the subprograms in the linked programs gets shifted
- Common area is put first followed by the sequence of remaining activation records: <common, (R<sub>1</sub>, L<sub>1</sub>), ..., (R<sub>N</sub>, L<sub>N</sub>)>

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## Code After Linking



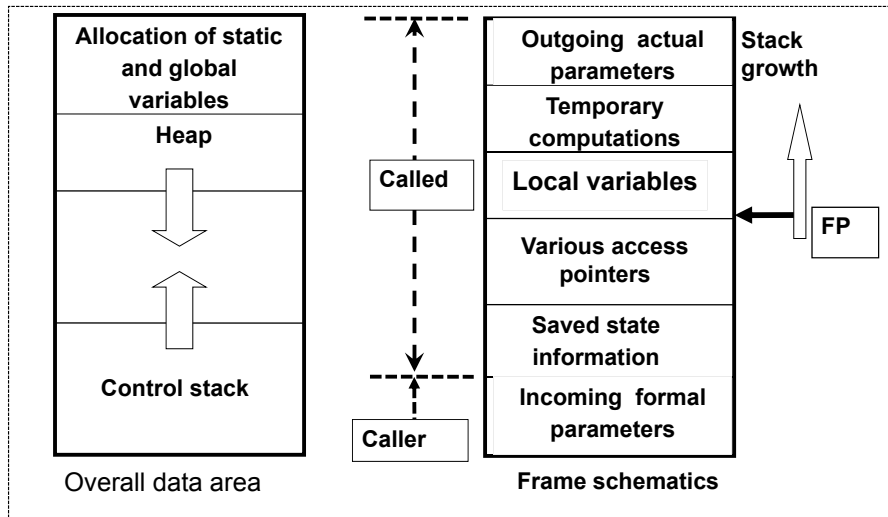
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## Hybrid Allocation

- Hybrid allocation combines various allocation schemes
  - Static memory that remains fixed during runtime, and is efficiently accessed using direct access. Static variables can be local or global
  - Frames allocated on the stack when a subprogram is invoked, and released when the subprogram is over
  - Dynamic data structures in heap
- Frame contains
  - Local dynamic stack variables
  - Saved state information of the calling program such as pointers, registers to be modified in the called programs
  - Incoming parameter space and outgoing parameter space
  - Space for scratchpad computation
- Pointers
  - 1) frame pointer, 2) dynamic link, 3) static link, 4) return pointer, 5) top of the stack pointer
- Incoming parameter space of the called subprogram and the outgoing parameter space of the calling programs overlap

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## Data Area – Block Structured Language



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## Roles of Various Pointers

- Current Frame pointer (FP)
  - Used to access the data area of the currently executing subprogram.
  - Points to the first memory location of the frame.
- Top of the stack pointer (ToS)
  - Used to point to the first free location in the stack.
- Return Pointer (RP)
  - Used to access the next instruction of the calling subprogram after return from the called subprogram.
  - Stored in the frame of the called subprogram since the same subprogram can be called multiple times.
- Dynamic Link (Previous Frame Pointer)
  - Points to the first memory location of the frame of the calling subprogram
  - Used to return the access of the frame of the calling subprogram back
- Static link (SL)
  - Points to the frame of the subprogram under which currently executing subprogram is nested to access the nonlocal dynamic variables

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## Calling Subprograms

### ■ Program invocation

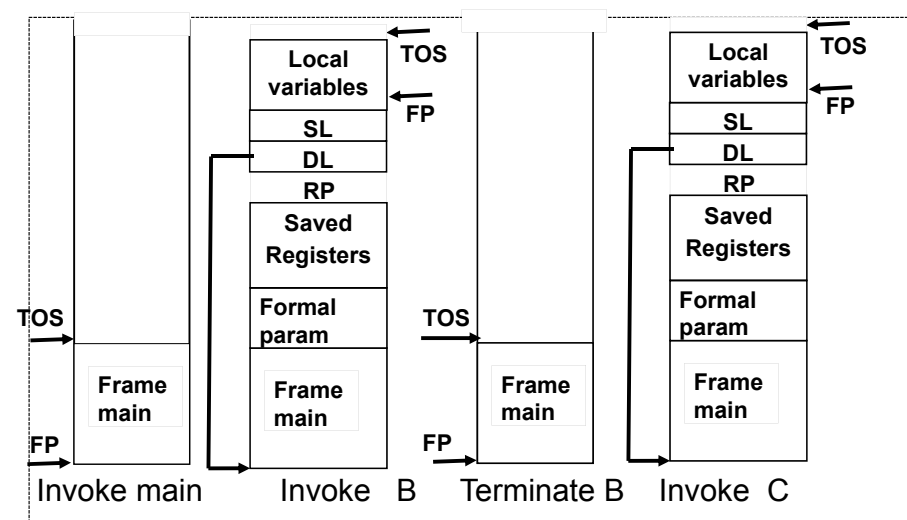
- Exchange the information between the calling and the called subprogram.
- Save the PSW and registers to be modified.
- The memory location of next instruction is pushed the control stack.
- Calling program's frame pointer is pushed in the control stack.
- The static link is set and pushed in the control stack.
- The current TOS value is copied in the frame pointer.
- IP is set to the location of the first instruction in the called subprogram.
- TOS is incremented by activation record size in the called subprogram

### ■ Return from the subprogram

- Copy the saved registers back of the calling subprogram.
- Set the FP back to the previous frame pointer using dynamic link.
- Reclaim the data area of the called subprogram by resetting the TOS pointer back to the TOS of the calling subprogram's TOS.
- Set IP to the value stored in the return pointer to jump back to the next instruction in the calling program.
- Copy the parameter values from outgoing parameter locations.

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## Frames During Procedure Calls

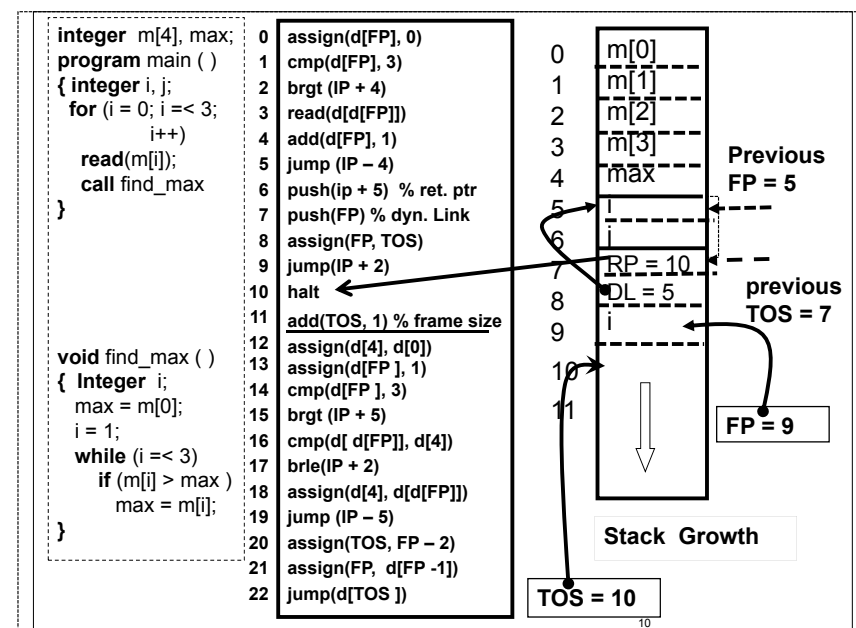


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## Generating Data and Code Areas

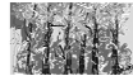
- Individual programs are compiled to generate the low level compiled code with embedded activation record.
- During linking code area is joined together in the order of user specification to make a bigger code area.
- The information about the return pointer and the first instruction pointer is set up from symbol table during linking process.
- Access to data area is embedded in the code area.
- During program invocation frame of the called program is placed on top of the stack.
- After program termination, the memory location of the frame is recovered.
- The offset of the pointers RP, DL, SL are negative.
- FP points to the first memory location where the local variables start.

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## Implementing Parameter Passing



- Outgoing parameter space of the calling subprogram and incoming parameter space of the called subprogram overlap
  - Calling program writes into its outgoing parameter space
  - Called program reads and updates its incoming parameter space
- Formal parameters are allocated in incoming parameter space of the called program
  - Call by value, call by result and call by value-result creates local variables for formal parameters in incoming parameter space
  - Call by reference creates pointers as formal parameters in the incoming parameter space
- Offset scheme
  - The offset of the formal parameter space, the saved register space and the pointers is negative.
  - The offset of locally declared variables and scratch pad computation space is positive

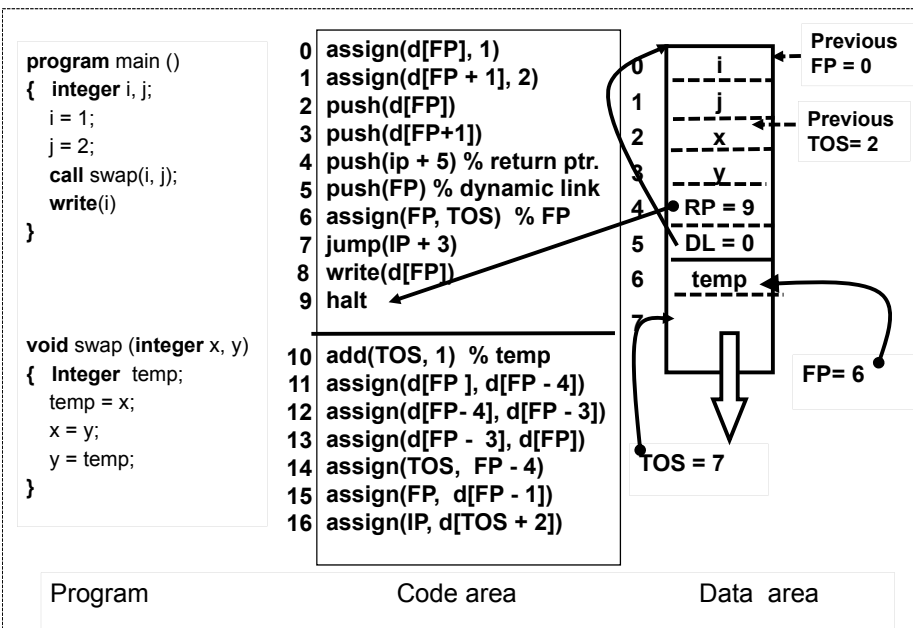
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## Implementing Call by Value



- The expression is evaluated and copied into the outgoing parameter space of the calling program
- The outgoing parameter space of the calling program becomes incoming formal parameter space of the called subprogram
  - Actual parameter is copied into formal parameter space using a statement `assign([FP + offset1], [FP + offset2])` where `offset1` is the offset of the actual parameter and `offset2` is the offset of the outgoing parameter location.
- Offset of the parameter space
  - The offset of the formal parameter space in called subprogram is negative with respect to the frame pointer.
  - The access to formal parameters is `d[FP + Offset]` where `offset` is negative.

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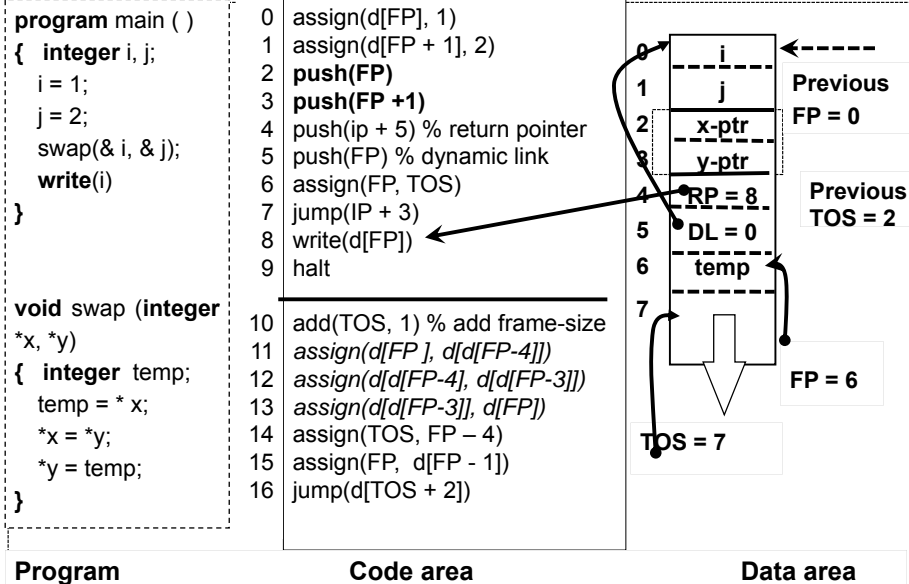
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## Implementing Call-by-Reference



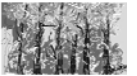
- A pointer is created in the outgoing parameter space of the calling procedure that
  - Points to the first memory location of the actual parameter.
  - Elements in actual parameters are accessed using `d[d[FP + offset1] + offset2]` where `offset1` is negative and `offset2` is positive.
  - `Offset1` is negative because the formal parameter is allocated before the activation record.
  - `Offset2` is positive as it is used to access the fields or elements in the actual parameter that is part of the activation record of the calling subprogram.
- Setting up of the formal parameter
  - Formal parameter is set by the statements `assign(d[FP + offset1], FP + offset2)` where `offset1` is the offset of the outgoing parameter and `offset2` is the offset of the actual parameter in the frame of the calling program.
  - Formal parameters are set in the calling program.
- There is no need to copy any result back

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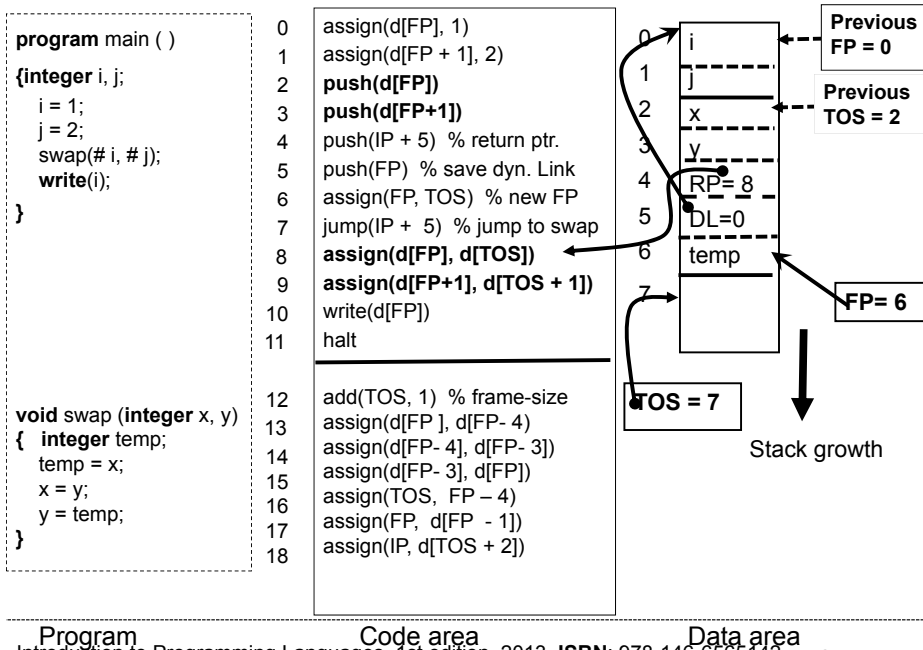
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## Implementing Call by Value-Result



- The expression is evaluated and copied into the outgoing parameter space of the calling program
- The outgoing parameter space of the calling program becomes incoming formal parameter space of the called subprogram
  - Actual parameter is copied into formal parameter space using a statement `assign([FP + offset1], [FP + offset2])` where `offset1` is the offset of the actual parameter and `offset2` is the offset of the outgoing parameter location
- The offset of the formal parameter space in called subprogram is negative with respect to the frame pointer.
- The access to formal parameters is `d[FP + Offset]` where `offset` is negative.
- After coming from the called subprogram
  - Formal parameter is copied into actual parameter using a statement `assign([FP + offset1], [FP + offset2])` where `offset1` is the offset of the formal parameter in outgoing parameter space and `offset2` is the offset of the actual parameter.

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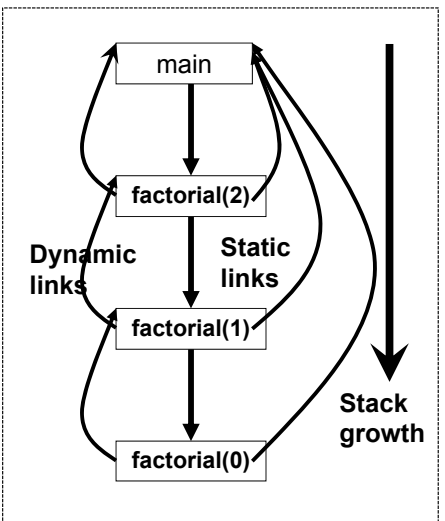


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## Behavior of Recursive Procedures



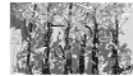
- Every invocation creates a new frame on top of the stack
- There is no access of the environment of multiple invocations of recursive procedures
- Static link of all invocation of a self recursive procedure point to the subprogram under which it is nested
- Dynamic link of a of a self recursive procedure points to the frame of previous invocation
- Recursive procedures have additional overhead of
  - Saving computational state of previous invocation



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# Implementing Exception Handlers



- **Exception handling techniques**
  - First technique is using the same control stack, exception flag and the use of branching instructions
  - Second technique is to keep a separate exception stack
- **First technique**
  - Use an exception flag that is set in case of the exceptional condition
  - After the exception flag is set the control returns to the calling subprogram with exceptional handler, and exception handler is executed
  - If exception flag is not set then a branch instruction is used to skip the exception handler
  - After the successful execution of an exception handler, the control remains in the same subprogram with exception handler
- **Second technique**
  - The address of the first instruction to the exception handler and the topmost activation frame is pushed on the execution stack.
  - After executing the exception-handler, all the frames above the frame of the successful exception handler are removed from the control stack.

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# Summary I



- Abstract machine contains code area, data area instruction pointer, and registers
- High level instructions are transferred to a sequence of low level instructions
- Conditional and iterative constructs are transferred using the control flow diagram and translation to low level instructions
- Memory allocation scheme is a combination of static allocation, stack based dynamic allocation, and heap based dynamic allocation
  - Static allocation has advantage of direct access but does not support recursive procedures and recursive data structures
  - Stack based allocation supports memory reuse and recursive procedures. However, does not support recursive and dynamic data structures
  - Heap based allocation is most general. However, it has overhead of memory recycling
- Block structured languages are implemented using hybrid allocation

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# Summary II



- **Hybrid allocation uses**
  - Static allocation for static local variables and global variables
  - Uses stack for dynamic local variables and saved computational state
  - Heap for the recursive data structures and dynamic objects
- **Parameter passing implementation**
  - Outgoing parameter space of the calling program is the same as incoming parameter space of the called program
  - The offset of the incoming parameter space and the saved computational state on the stack is negative
  - The offset of the local dynamic variable of the called subprogram is positive
  - Call by value and call by value-result evaluates the expression, and copies the value from the evaluated expression to outgoing parameter space
  - Call by reference copies the location of the actual parameter to the outgoing parameter space

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